



Inverter and DC Buck Efficiency

This application report provides a step-by-step procedure for calculating buck converter efficiency and power dissipation at operating points not provided by the data sheet. This application report provides a step-by-step procedure for calculating buck converter efficiency and power dissipation at operating points not provided by the data sheet. Texas Instruments has a large portfolio of DC/DC converters which operate over a wide range of input and output voltages. Switching regulators are known as being highly efficient power sources. To further improve their efficiency, it is helpful to understand the basic mechanism of power loss. This application note explains power loss factors and methods for calculating them. It also explains how the relative importance of power loss factors varies with operating conditions. Determining the best match between an inductor and an IC is paramount to achieving the best performance in terms of PCB space, as well as thermal and cost efficiency. Let's explore which parameters are most important when designing a buck (step-down) converter, and how to pair it with the best. The inverting buck/boost converter topology is an often mysterious and misunderstood category of DC/DC converters. This document attempts to remove any misconception around the circuit by providing a step-by-step design procedure with equations, schematics, simulations and considerations to ensure accurate analysis. Applying traditional circuit analysis techniques, this paper proposes a new approach to model the steady state operating conditions of the DC/DC buck-boost power converters. The developed approach can be more or less considered new because it is not present in the literature, sometimes it is. Generating a negative output voltage rail from a positive input voltage rail can be done by reconfiguring an ordinary buck regulator. The result is an inverting buck-boost (IBB) topology implementation. This application report gives details regarding this conversion with examples. Figure 2-1. Efficiency of Buck Converter Application Note

Dead time loss
Conduction loss in the inductor
Total power loss
Calculation example (synchronous rectification type)
Non-synchronous rectification type
Conduction loss in the diode
Calculation example (non-synchronous rectification type)

OUTPUT CURRENT : IO [A]
SW f [Hz]
OUTPUT VOLTAGE : VOUT [V]
VIN = 10V
IO = 1A
fSW = 1MHz
L = 4.7uH (DCR = 80m?)
High-side MOSFET RON = 100m?
Low-side MOSFET RON = 70m?
VIN = 10V
IO = 1A
fSW = 1MHz
L = 4.7uH (DCR = 80m?)
MOSFET RON = 100m?

Switching Regulator IC Series

Switching regulators are known as being highly efficient power sources. To further improve their efficiency, it is helpful to understand the basic mechanism of power loss. This application note explains power loss factors and methods for calculating them. It also explains how the relative importance of power loss factors varies with operating conditions. See more on [fscdn.rohm](#)



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dissipation at operating points not provided by the data sheet. Efficiency of Buck Converter To further improve their efficiency, it is helpful to understand the basic mechanism of power loss. This application note explains power loss factors and methods for calculating them. A Perfect Match: Power Losses in Buck Converters and How to Taking care of a few design parameters is the key to successfully choosing an inductor that works well with a buck converter, and to avoiding power losses and increasing efficiency. AN-: The Design of the Inverting Buck/Boost Converter The inverting buck/boost converter can be asynchronous if a diode is used and synchronous if the diode is replaced with a metal-oxide semiconductor field-effect transistor (MOSFET), which A Perfect Match: Power Losses in Buck Converters and How Since modern buck converters have switch on resistances that range from tens to hundreds of m Ω , the best performance can be matched with small and highly conductive power inductors

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